

Parallel Programming Laboratory  
University of Illinois at Urbana-Champaign

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# CONVERSE Programming Tutorial

CONVERSE Parallel Programming Environment was developed as a group effort at Parallel Programming Laboratory, University of Illinois at Urbana-Champaign.

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Version 1.0

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# Chapter 1

## Introduction

### 1.1 CthThreads

The CthThread package, like most thread packages, provides basic functionality for creating threads, destroying threads, yielding, suspending, and awakening a suspended thread. In addition, it provides facilities whereby you can write your own thread schedulers.

Figure ?? demonstrates how to write a simple program that creates CthThreads. The `CthCreateMigratable` is used and it takes a handler, an argument pointer, and the stack size for the thread. This is demonstrated in the `initThreads` function on line number 43. Once the threads are created, they are pushed on the scheduler queue with the `CthAwaken` call, which only takes the `CthThread` as an argument. On being scheduled, the handler function is called.

In the example, each thread then calls `CthYield`, which directs control back to the scheduler and pushes the thread back onto the queue. Then in a loop, each thread calls `CthYieldPrio` `NUM_YIELD` times, with the queuing strategy and necessary parameters. The threads call this with priority 0 and 1, lower integers (but non-negative) indicating higher priority. The effect of yielding with priority is that the higher priority thread on the queue has precedence over the other threads and hence will be scheduled first, based on the greedy decision the scheduler makes.

After this loop completes, the `threadDone` is called by each thread, which increments a counter and quits the program when all threads are done.

```

1  #include <converse.h>
2  #include <stdlib.h>
3  CpvDeclare(int ,msgSize);
4  CpvDeclare(int ,exitHandler);
5  CpvDeclare(int ,node0Handler);
6  CpvDeclare(int ,node1Handler);
7  void startRing()
8  {
9      char *msg = (char *)CmiAlloc(CpvAccess(msgSize));
10     *((int *) (msg+CmiMsgHeaderSizeBytes)) = CpvAccess(msgSize);
11     CmiSetHandler(msg,CpvAccess(node1Handler));
12     CmiSyncSendAndFree(1, CpvAccess(msgSize), msg);
13 }
14 void ringFinished(char *msg)
15 {
16     CmiFree(msg);
17     //exit
18     void *sendmsg = CmiAlloc(CmiMsgHeaderSizeBytes);
19     CmiSetHandler(sendmsg,CpvAccess(exitHandler));
20     CmiSyncBroadcastAllAndFree(CmiMsgHeaderSizeBytes,sendmsg);
21 }
22 //We finished for all message sizes. Exit now
23 CmiHandler exitHandlerFunc(char *msg)
24 {
25     CmiFree(msg);
26     CsdExitScheduler();
27     return 0;
28 }
29 //Handler on Node 0
30 CmiHandler node0HandlerFunc(char *msg)
31 {
32     ringFinished(msg);
33     return 0;
34 }
35 CmiHandler node1HandlerFunc(char *msg)
36 {
37     CpvAccess(msgSize) = *((int *) (msg+CmiMsgHeaderSizeBytes));
38     CmiSetHandler(msg,CpvAccess(node0Handler));
39     CmiSyncSendAndFree(0,CpvAccess(msgSize),msg);
40     return 0;
41 }
42 CmiStartFn mymain()
43 {
44     CpvInitialize(int ,msgSize);
45     CpvAccess(msgSize)= 512 + CmiMsgHeaderSizeBytes;
46     CpvInitialize(int ,exitHandler);
47     CpvAccess(exitHandler) = CmiRegisterHandler((CmiHandler) exitHandlerFunc);
48     CpvInitialize(int ,node0Handler);
49     CpvAccess(node0Handler) = CmiRegisterHandler((CmiHandler) node0HandlerFunc);
50     CpvInitialize(int ,node1Handler);
51     CpvAccess(node1Handler) = CmiRegisterHandler((CmiHandler) node1HandlerFunc);
52     if (CmiMyPe() == 0)
53         startRing();
54     return 0;
55 }
56 int main(int argc, char *argv[])
57 {
58     ConverseInit(argc,argv,(CmiStartFn)mymain,0,0);
59     return 0;
60 }

```

Figure 1.1: A Pingpong Example using Converse Handler

```

1  #include <stdio.h>
2  #include "converse.h"
3
4  #define HIGH_PRIO 0
5  #define LOW_PRIO 1
6  #define NUM_YIELD 10
7
8  int endCounter = 0;
9
10 //determine completion based on threads calling it
11 void threadDone() {
12     endCounter++;
13     if (endCounter == 2) CsdExitScheduler();
14 }
15
16 //worker function for worker1, yields with a low priority
17 void worker1Work(void* msg) {
18     printf("start worker1\n");
19     CthYield();
20     printf("worker1 resumed first time\n");
21     unsigned int prio = LOW_PRIO;
22     for(int i = 0; i < NUM_YIELD; i++) {
23         CthYieldPrio(CQS_QUEUEING_IFIFO,0,&prio);
24         printf("worker1 resumed %dth time\n",i);
25     }
26     threadDone();
27 }
28
29 //worker function for worker2, yields with a high priority
30 void worker2Work(void* msg) {
31     printf("start worker2\n");
32     CthYield();
33     printf("worker2 resumed first time\n");
34     unsigned int prio = HIGH_PRIO;
35     for(int i = 0; i < NUM_YIELD; i++) {
36         CthYieldPrio(CQS_QUEUEING_IFIFO,0,&prio);
37         printf("worker2 resumed %dth time\n",i);
38     }
39     threadDone();
40 }
41
42 //create two worker threads and push them on scheduler Q
43 void initThreads(int argc, char* argv[]) {
44     printf("called initThreads\n");
45     CthThread worker1 = CthCreateMigratable((CthVoidFn)worker1Work, 0, 160000);
46     CthThread worker2 = CthCreateMigratable((CthVoidFn)worker2Work, 0, 160000);
47     CthAwaken(worker1); CthAwaken(worker2);
48 }
49
50 int main(int argc, char* argv[]) {
51     ConverseInit(argc, argv, initThreads, 0, 0);
52 }

```

Figure 1.2: CthThread Example